

06:00 (UTC +1) Poster Session 1

Poster interaction - Dedicated time slots for presenters, On Demand Video Viewing, Virtual Exhibition, Demonstrations

Monday	Monday	Monday	Monday	Monday	Monday	Monday	Monday	Sunday	Monday
UK UTC +1 Hour	Europe UTC +2 Hours	Dubai UTC +4 Hours	India UTC +5.30 hours	Hong Kong UTC +8 Hours	Japan UTC +9 Hours	Sydney UTC +10 Hours	New Zealand UTC +12 Hours	San Francisco UTC -7 Hours	Boston UTC -4 Hours
06:00	07:00	09:00	10:30	13:00	14:00	15:00	17:00	22:00	01:00
Poster Session	Poster Session	Poster Session	Poster Session	Poster Session	Poster Session	Poster Session	Poster Session		

Poster Session 06:00 - 08:00 (UTC +1)
Demonstrations 06:00 - 08:00 (UTC +1)

07:20 (UTC +1) Conference Opening Session

Monday	Monday	Monday	Monday	Monday	Monday	Monday	Monday	Sunday	Monday
UK UTC +1 Hour	Europe UTC +2 Hours	Dubai UTC +4 Hours	India UTC +5.30 hours	Hong Kong UTC +8 Hours	Japan UTC +9 Hours	Sydney UTC +10 Hours	New Zealand UTC +12 Hours	San Francisco UTC -7 Hours	Boston UTC -4 Hours
07:20	08:20	10:20	11:50	14:20	15:20	16:20	18:20	23:20	02:20
ECCV 2020 Welcome from General Chairs									
ECCV 2020 Update from Program Chairs									
ECCV 2020 Prizes									

08:00 (UTC +1) Live Session 1 with Q&A

Monday	Monday	Monday	Monday	Monday	Monday	Monday	Monday	Monday	Monday
UK UTC +1 Hour	Europe UTC +2 Hours	Dubai UTC +4 Hours	India UTC +5.30 hours	Hong Kong UTC +8 Hours	Japan UTC +9 Hours	Sydney UTC +10 Hours	New Zealand UTC +12 Hours	San Francisco UTC -7 Hours	Boston UTC -4 Hours
08:00	09:00	11:00	12:30	15:00	16:00	17:00	19:00	00:00	03:00
Oral Session - 3D geometry & reconstruction					Spotlight Session - Recognition & detection				
Industry News					Industry News				
Feihu Zhang	Domain-invariant Stereo Matching Networks			#2344	Kaiwen Duan	Corner Proposal Network for Anchor-free, Two-stage Object Detection			#3012
Marie-Julie Rakotosaona	Intrinsic Point Cloud Interpolation via Dual Latent Space Navigation			#3199	Tong Wu	Distribution-Balanced Loss for Multi-Label Classification in Long-Tailed Datasets			#3051
Yida Wang	SoftPoolNet: Shape Descriptor for Point Cloud Completion and Classification			#1141	Zhiming Chen	PloU Loss: Towards Accurate Oriented Object Detection in Complex Environments			#3092
					Liuyu Xiang	Learning From Multiple Experts: Self-paced Knowledge Distillation for Long-tailed Classification			#4123
					Guosen Xie	Region Graph Embedding Network for Zero-Shot Learning			
Elevator pitches					Elevator pitches				
Live Q&A					Live Q&A				

08:40 - 08:50 (UTC +1) Rest Break

08:50 (UTC +1) Live Session 1 with Q&A

Oral Session - 3D geometry & reconstruction					Spotlight Session - Recognition & detection				
"Promo Pitches" from Industry					"Promo Pitches" from Industry				
Heming Zhu	Deep Fashion3D: A Dataset and Benchmark for 3D Garment Reconstruction from Single Images			#3065	Minchul Kim	Learning Visual Context by Comparison			#2171
Garvita Tiwari	SIZER: A Dataset and Model for Parsing 3D Clothing and Learning Size Sensitive 3D Clothing			#3209	Yixiao Ge	Self-supervising Fine-grained Region Similarities for Large-scale Image Localization			#2078
Dylan Campbell	Solving the Blind Perspective-n-Point Problem End-To-End With Robust Differentiable Geometric Optimization			#3099	Sho Inayoshi	Bounding-box Channels for Visual Relationship Detection			#4161
Yizhak Ben-Shabat	DeepFit: 3D Surface Fitting via Neural Network Weighted Least Squares			#4004	Jae Sung Park	VisualCOMET: Reasoning about the Dynamic Context of a Still Image			#2153
					Wenshuo Ma	AABO: Adaptive Anchor Box Optimization for Object Detection via Bayesian Sub-sampling			#3121
					Jiaqi Wang	Side-Aware Boundary Localization for More Precise Object Detection			#4074
Live Q&A					Live Q&A				

09:30 (UTC +1) Networking Break

Industry Sessions, On Demand Video Viewing, Virtual Exhibition, Networking, Live Chat

Monday	Monday	Monday	Monday	Monday	Monday	Monday	Monday	Monday	Monday
UK UTC +1 Hour	Europe UTC +2 Hours	Dubai UTC +4 Hours	India UTC +5.30 hours	Hong Kong UTC +8 Hours	Japan UTC +9 Hours	Sydney UTC +10 Hours	New Zealand UTC +12 Hours	San Francisco UTC -7 Hours	Boston UTC -4 Hours
09:30	10:30	12:30	14:00	16:30	17:30	18:30	20:30	01:30	04:30
Chat with Chairs									
Chat with Chairs									
09:30 - 10:30 (UTC +1)									
Visit the Networking Lounge and 'Start a Chat'									
Monday Yoga with Claire									
09:30 - 10:30 (UTC +1)									
Visit 'ECCV'20 Fun Things' within the Networking Lounge									
Industry Session									
Baidu									
10:45-11:15 (UTC +1)									
Topic 1: Vision Techs in AI-city Baidu									
Topic 2: Building High-Quality Custom AI Models Without Having to Code									
Topic 3: 3D Perception and Planning for Autonomous Driving and Robotics									
Industry Session									
Sony									
11:30-12:15 (UTC+1)									
Technology foundation for Real-time, Reality and Remote									
Topic 1: Intelligent Vision Sensor, Seigo Hirakawa (Sony Semiconductor Solutions)									
Topic 2: Online and Offline 3D Mapping, Andreas Kuhn (Sony R&D Center)									
Topic 3: Sony AI, Peter Duerr (Sony AI)									

12:30 (UTC +1) Live Session 2 with Q&A

Monday	Monday	Monday	Monday	Monday	Monday	Monday	Monday	Monday	Monday
UK UTC +1 Hour	Europe UTC +2 Hours	Dubai UTC +4 Hours	India UTC +5.30 hours	Hong Kong UTC +8 Hours	Japan UTC +9 Hours	Sydney UTC +10 Hours	New Zealand UTC +12 Hours	San Francisco UTC -7 Hours	Boston UTC -4 Hours
12:30	13:30	15:30	17:00	19:30	20:30	21:30	23:30	04:30	07:30
Oral Session - Recognition & detection					Spotlight Session - 3D geometry & reconstruction				
Industry News					Industry News				
Mengtian (Martin) Li	Towards Streaming Perception			#4349	Xiaobin Hu	Face Super-Resolution Guided by 3D Facial Priors			#1067
Jinlu Liu	Prototype Rectification for Few-Shot Learning			#4111	Frank Dellaert	Shonan Rotation Averaging: Global Optimality by Surfing SSO(p)^ns			#4409
Nicolas Carion	End-to-End Object Detection with Transformers			#3170	Hongwei Yi	Dense Hybrid Recurrent Multi-view Stereo Net with Dynamic Consistency Checking			#4105
					Philipp Erler	Points2Surf Learning Implicit Surfaces from Point Clouds			#1073
					Juan Du	DH3D: Deep Hierarchical 3D Descriptors for Robust Large-Scale 6DoF Relocalization			#1066
Elevator pitches					Elevator pitches				
Live Q&A					Live Q&A				

13:10 - 13:20 (UTC +1) Rest Break

13:20 (UTC +1) Live Session 2 with Q&A

Oral Session - Recognition & detection					Spotlight Session - 3D geometry & reconstruction				
"Promo Pitches" from Industry					"Promo Pitches" from Industry				
Hongjie Zhang	Hybrid Models for Open Set Recognition			#4197	Jiayong Peng	Photon-Efficient 3D Imaging with A Non-Local Neural Network			#4192
Georgios Toliass	Learning and Aggregating Deep Local Descriptors for Instance-level Recognition			#3176	Frank Verbiest	Modeling the Effects of Windshield Refraction for Camera Calibration			#1148
Ameya Prabhu	GDumb: A Simple Approach that Questions Our Progress in Continual Learning			#1093	Viktor Larsson	Calibration-free Structure-from-Motion with Calibrated Radial Trifocal Tensors			#1088
Haoyu Liang	Training Interpretable Convolutional Neural Networks by Differentiating Class-specific Filters			#2167	Songyou Peng	Convolutional Occupancy Networks			#1016
					Zuzana Kukelova	Minimal Rolling Shutter Absolute Pose with Unknown Focal Length and Radial Distortion			#1119
Live Q&A					Live Q&A				

14:00 (UTC +1) Poster Session 2 & Industry Session

Virtual Exhibition, Poster Interaction - Dedicated time slots for presenters, On Demand Video Viewing, Demonstrations

Monday	Monday	Monday	Monday	Monday	Monday	Monday	Tuesday	Monday	Monday
UK UTC +1 Hour	Europe UTC +2 Hours	Dubai UTC +4 Hours	India UTC +5.30 hours	Hong Kong UTC +8 Hours	Japan UTC +9 Hours	Sydney UTC +10 Hours	New Zealand UTC +12 Hours	San Francisco UTC -7 Hours	Boston UTC -4 Hours
14:00	15:00	17:00	18:30	21:00	22:00	23:00	01:00	06:00	09:00
Poster Session	Poster Session	Poster Session	Poster Session					Poster Session	Poster Session
Poster Session 14:00 - 16:00 (UTC +1)									
Demonstrations 14:00 - 16:00 (UTC +1)									
Industry Session - Huawei Research Center									
15:15 - 15:45 (UTC +1)									
Topic 1: Challenges and Opportunities for working in Huawei Research									
Topic 2: Computational Photography Challenges (Moire Challenge), AI Theory and CV, Multi-modal Dataset in Huawei London Research Center									
Topic 3: Mindspore, a highly parallelism and device-edge-cloud collaborated deep learning computing framework									

16:00 (UTC +1) Live Session 3 with Q&A

Monday	Monday	Monday	Monday	Monday	Tuesday	Tuesday	Tuesday	Monday	Monday
UK UTC +1 Hour	Europe UTC +2 Hours	Dubai UTC +4 Hours	India UTC +5.30 hours	Hong Kong UTC +8 Hours	Japan UTC +9 Hours	Sydney UTC +10 Hours	New Zealand UTC +12 Hours	San Francisco UTC -7 Hours	Boston UTC -4 Hours
16:00	17:00	19:00	20:30	23:00	00:00	01:00	03:00	08:00	11:00
Oral Session - 3D geometry & reconstruction					Spotlight Session - Recognition & detection				
Industry News					Industry News				
Stefan Popov	CoReNet: Coherent 3D Scene Reconstruction from a Single RGB Image			#1084	Malik Bouadif	A unifying formal information view of metric learning: cross-entropy vs. pairwise losses			#4427
Yifan Xu	Ladybird: Quasi-Monte Carlo Sampling with Deep Implicit Field Based 3D Reconstruction with Symmetry			#1026	Daniel Bolya	TIDE: A General Toolbox for Identifying Object Detection Errors			#2282
Pratul Sriniwasan	NeRF: Representing Scenes as Neural Radiance Fields for View Synthesis			#4278	Fariborz Taherkhani	Transporting Labels via Hierarchical Optimal Transport for Semi-Supervised Learning			#4309
					Angelina Wang	REVISE: A Tool for Measuring and Mitigating Bias in Visual Datasets			#4261
					Xingyi Zhou	Tracking Objects as Points			#3260
Elevator pitches					Elevator pitches				
Live Q&A					Live Q&A				

16:40 - 16:50 (UTC +1) Rest Break

16:50 (UTC +1) Live Session 3 with Q&A

Oral Session - 3D geometry & reconstruction					Spotlight Session - Recognition & detection				
"Promo Pitches" from Industry					"Promo Pitches" from Industry				
Bharat Lal Bhatnagar	Combining Implicit Function Learning and Parametric Models for 3D Human Reconstruction			#1078	Aditya Tripathi	Sketch-Guided Object Localization in Natural Images			#3221
George Terzakis	A Consistently Fast and Globally Optimal Solution to the Perspective-n-Point Problem			#2307	Titir Dutta	Adaptive Margin Diversity Regularizer for handling Data Imbalance in Zero-Shot SBR			#1085
James Watson	Learning Stereo from Single Images			#4318	Zuxuan Wu	Making an Invisibility Cloak: Real World Adversarial Attacks on Object Detectors			#2294
Jingjing Shen	The Phong Surface: Efficient 3D Model Fitting using Lifted Optimization			#4316	Arman Afrasiyabi	Associative Alignment for Few-shot Image Classification			#1174
					Arun Balajee Vasudevan	Semantic Object Prediction and Spatial Sound Super-Resolution with Binaural Sounds			#2255
Live Q&A					Live Q&A				

17:30 (UTC +1) Networking Break

Industry Sessions, On Demand Video Viewing, Virtual Exhibition, Networking, Live Chat

Monday	Monday	Monday	Monday	Tuesday	Tuesday	Tuesday	Tuesday	Monday	Monday
UK UTC +1 Hour	Europe UTC +2 Hours	Dubai UTC +4 Hours	India UTC +5.30 hours	Hong Kong UTC +8 Hours	Japan UTC +9 Hours	Sydney UTC +10 Hours	New Zealand UTC +12 Hours	San Francisco UTC -7 Hours	Boston UTC -4 Hours
17:30	18:30	20:30	22:00	00:30	01:30	02:30	04:30	09:30	12:30
Industry Session									
Lyft									
17:45-18:30 (UTC +1)									
Solving the Next Great Challenges in Self-Driving									
Industry Session									
Amazon									
18:45-19:15 (UTC +1)									
Scholars & Computer Vision @ Amazon									